## A Primal method for the Assignment Problem

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## Abstract

This paper describes a primal method for the assignment problem. The algorithm is based on a "Tomizawa-step", making at least one column of the relative-cost matrix dual feasible. So the total number of steps is less than or equal to $n$, the problem size.
The number of degenerate pivots is negligible. The advantages of a primal method are well-known: in each stage of the calculation a feasible assignment is available and the process can be started with a "good" primal solution. Computational experience is given.

[^0]1. Introduction

We consider the linear assignment problem and its dual

$$
\begin{array}{ll}
\operatorname{Min} \sum_{i j} a_{i j} x_{i j} & \operatorname{Max} \sum_{i} u_{i}+\sum_{j} v_{j} \\
\text { s.t. } \sum_{j} x_{i j}=1 & i=1, \ldots, n \\
\sum_{i} x_{i j}=1 & \text { s.t. } u_{i}+v_{j} \leqslant a_{i j} \\
\quad x_{i j} \geqslant 0 & i=1, \ldots, n \\
i=1, \ldots, n \\
j=1, \ldots, n
\end{array}
$$

The best known algorithm for solving this problem is perhaps the primaldual algorithm of Tomizawa, revised by Dorhout [2]. Essential is the use of Dijkstra's shortest path method, as in the relaxation method of Hung and Rom [ 3]. Balinski and Gomory [1] introduced a primal method, with the advantage of having a complete feasible assignment in each step of the algorithm. Primal methods like the simplex method usually require many degenerate steps.
In [ 3] computational experience is mentioned, showing that also the modified simplex method of Balinski and Gomory is still suffering from it.
In the present method the number of degenerate steps, where the primal solution does not change, is negligible. In one step at least one column of the reduced-cost matrix is made dual feasible, where several degenerate steps in the method of Balinski and Gomory are needed.
2. A primal method

Suppose that a primal solution $\left\{x_{i j}\right\}$ with some corresponding dual solution $\left\{u_{i}, v_{j}\right\}$ is at hand, either found during the calculation or constructed in some other way, with at least one negative entry $\bar{a}_{i j}=a_{i j}-u_{i}-v_{j}$ of the corresponding reduced-cost matrix. So the dual solution is not feasible, that means the primal solution is not optimal.
Select a column $j_{0}$ with some $\mathrm{a}_{\mathrm{ij}} \mathrm{j}_{0}<0$ and choose $\mathrm{i}_{0}$ such that

$$
\bar{a}_{i_{0} j_{0}}=\operatorname{Min}_{i}\left\{\bar{a}_{i j_{0}} \mid \bar{a}_{i j_{0}}<0\right\}
$$

and make

$$
v_{j_{0}}:=v_{j_{0}}+a_{i_{0} j_{0}}{ }^{1)} \text { resp. } \bar{a}_{i j_{0}}:=\bar{a}_{i j_{0}}-\bar{a}_{i_{0} j_{0}} \geqslant 0 \text { for } i=1, \ldots, n
$$

Next we look for the best corresponding primal solution.
Consider the momentary primal solution and cancel the assignment in column $j_{0}$ and let us say row $i_{1}$. The shortest path from row $i_{1}$ to column $j_{0}$ can be found by using a slightly revised "Tomizawa"-step. See steps 4, 5 and 6 of the revised algorithm in [2]. Essential for our method is keeping all nonnegative $\bar{a}_{i j}$ nonnegative. This can be achieved by using only the nonnegative entries of the reduced cost matrix. The result is a new complete assignment, with at least column $j_{0}$ as an extra dual feasible column. Therefore the algorithm terminates in at most $n$ steps. Degeneracy only occurs when element ( $i_{1}, j_{0}$ ) gives the shortest path between row $i_{1}$ and column $j_{0}$.
The validity of the algorithm is on the one hand based on the wellknown theorem that the optimal solution of the problem does not change when a constant is added to all elements of a row or column of the cost matrix. On the other hand we refer to the validation of the Tomizawa algorithm in [2]. Justification of the nonnegativity condition in this step, as applied in our method, is immediate.
3. The Algorithm
step 0. Initialization.
Start with a primal feasible solution $\left\{x_{i j}\right\}$
Define the labels $\xi_{i}=j$ and $\eta_{j}=\mathbf{i}$ iff $x_{i j}=1$ for $i=1, \ldots, n ; j=1, \ldots, n$
Construct a corresponding dual solution, e.g.
$u_{i}=0$ for $i=1, \ldots, n$
$v_{j}=a_{n_{j}, j}$ for $j=1, \ldots, n$
Reduce the cost matrix: $\begin{aligned} \bar{a}_{i j}:=a_{i j}-u_{i}-v_{j} \text { for } \begin{aligned} i & =1, \ldots, n \\ j & =1, \ldots, n\end{aligned}, ~\end{aligned}$
step 1. Column selection.
Determine $\bar{a}_{i_{0} j_{o}}=\operatorname{Min}_{i, j}\left\{\bar{a}_{i j} \mid \bar{a}_{i j}<0\right\}$
The method stops if all $\bar{a}_{i j} \geqslant 0$ : the solution is dual feasible, hence optimal.

1) $\mathrm{a}:=\mathrm{b}$ stands for ' a is replaced by b '
step 2. Preparation for Tomizawa-step:
Make $\Delta v_{j_{0}}:=\bar{a}_{i_{0} j_{0}}$ and $\bar{a}_{i j_{0}}:=\bar{a}_{i j_{0}}-\Delta v_{j_{0}}$ for $i=1, \ldots, n$

$$
v_{j_{0}}:=v_{j_{0}}+\bar{a}_{i_{0} j_{0}}
$$

Cancel the assignment in column $j_{0}$ and row $\eta_{j_{0}}=i_{1}: \xi_{i_{1}}:=0$

$$
\eta_{j_{0}}:=0
$$

step 3. Tomizawa-step:
a. Define a set $T=\{1, \ldots, n\}$ and labels $\lambda_{i}=j_{0}$ for all $i \in T$ Make $\Delta u_{i}:=\bar{a}_{i j_{0}}$ for $i=1, \ldots, n$;

$$
\Delta v_{j_{0}}:=0 \text { and } \Delta v_{j}=\infty \text { for all } j \neq j_{0}
$$

b. If $\Delta u_{m}=\operatorname{Min}_{i}\left\{\Delta u_{i} \mid i \in T\right\}$ then go to $c$. in the case that $\xi_{\mathrm{m}}=0, \mathrm{~T}:=\mathrm{T}-\{\mathrm{m}\}, j:=\xi_{\mathrm{m}}, \Delta v_{j}:=\Delta u_{m}$. For all $i \in T$, with $\bar{a}_{i j} \geqslant 0$ and $\bar{a}_{i j}+\Delta v_{j}<\Delta u_{i}$, make $\lambda_{i}:=j$ and $\Delta u_{i}:=\bar{a}_{i j}+\Delta v_{j}$. Repeat this step.
c. Construct the shortest path from column $j_{0}$ to row $m$, using the labels $\lambda_{\mathbf{i}}$. The dual variables become:
$u_{i}:=u_{i}+\operatorname{Min}\left(\Delta u_{m}, \Delta u_{i}\right) \quad i=1, \ldots, n$ $v_{j}:=v_{j}-\operatorname{Min}\left(\Delta u_{m}, \Delta v_{j}\right) \quad j=1, \ldots, n$
And the reduced matrix: $\overline{\mathrm{a}}_{\mathbf{i j}}:=\overline{\mathrm{a}}_{\mathbf{i j}}-\mathrm{u}_{\mathbf{i}}-\mathrm{v}_{\mathrm{j}}$ for $\mathrm{i}=1, \ldots, n$; $j=1, \ldots, n$
After this step the assignment is complete again and at least column $j_{0}$ is feasible. Meanwhile all other nonnegative elements $\bar{a}_{i j}$ remain feasible. Go to step 1.
4. Example

Consider the assignment problem from [2], defined by the cost matrix (see fig. 1).
step 0. Start with $x_{i j}=1, u_{i}=0, v_{i}=a_{i j}$ assigned cells are encircled.
step 1. $\bar{a}_{i_{0} j_{0}}=\bar{a}_{54}=-8$

$\Delta v_{j} \not \begin{array}{lllll}\infty & \infty & \infty & \infty & 0 \\ 0 & 0 & 0 & 0 & \end{array}$



$$
\begin{array}{cccccc}
\Delta v_{j} & \infty & \infty & 0 & \infty & \infty \\
& 0 & 0 & & 1 & 0
\end{array}
$$

$$
\begin{aligned}
& v_{j}
\end{aligned}
$$

fig. 1. Example.
step 2. $\Delta v_{4}=-8$ is used in column 4 , assignment $(4,4)$ is cancelled
step 3a. Labels $\lambda_{i}$ are mentioned in the left-hand margin, $\Delta v_{4}=0$.
step 3b. $\Delta u_{m}=\Delta u_{5}=0, j=5$. The order of computation is given between brackets. $\Delta v_{5}=0$, no labels are changed by column 5 . $\Delta u_{m}=\Delta u_{2}=2, j=2, \Delta v_{2}=2$, change $\Delta u_{1}=4, \quad \lambda_{1}=2$ and $\Delta u_{4}=5, \lambda_{4}=2 . \Delta u_{m}=\Delta u_{1}=4, \Delta v_{1}=4$, no labels changed. $\Delta u_{m}=\Delta u_{4}=5$. Go to step 3c.
step $3 c . \quad \Delta u_{m}=5$ so $\Delta v_{3}=5$ and $\Delta u_{3}=5$
Column 4 is feasible, but also columns 1 and 2. Go to step 1 .
In the next iteration the cost matrix is not changed, but the primal solution is. After one more iteration the optimum is found. The number of iterations is 3 . There are no degenerate steps.
5. Computational Experience

The algorithm is tested against the primal method of Balinski and Gomory
[ 1] and the dual method of Tomizawa, improved by Dorhout [ 2]. The last one being the best method at present, at least in my knowledge. The first one was merely used as a starting point in my search for a primal method. Experience with this algorithm in [3] shows that more than $90 \%$ of the pivots in the problems tested are degenerate. In our method the number of degenerate pivots, these are iteration steps where the primal solution does not change, is negligible. Several degenerate steps needed to make a column of the reduced-cost matrix dual feasible are contracted to one step in the present method. Therefore in the computations we only compared with the Tomizawa method.
In order to get a fair comparison we programmed this method in a similar way as the proposed algorithm. The advantages of the present method, giving a primal feasible solution at each stage of the calculation and enabling to start with a known "good" primal solution, cannot be shown in computer results. However we can test average behaviour against the Tomizawa method.

Three initialization methods were used:
$\left(I_{1}\right): x_{i j}=1$ for $i=1, \ldots, n$ and $x_{i j}=0$ for $i \neq j$
$\left(I_{2}\right): x_{i j}=1$ if $a_{i j}=\operatorname{Min}_{k}\left\{a_{k j} \mid\right.$ no assignment in row $\left.k\right\}$, successivily for $\mathrm{j}=1, \ldots, \mathrm{n}$.
$\left(\mathrm{I}_{3}\right)$ : After row- and columnreduction and straightforward assignment of independent zeroes (see [2]) use method $I_{2}$ for not-assigned rows and columns.

The algorithm was programmed in Basic and run on a VAX $11 / 750$ time-sharing system. The test problems are randomly generated with cost coefficients between 1 and 99. The results shown in Table I come from fixed problems. The results in Table II are average results over each 5 randomly generated problems.

In order to test the sensitivity for variation in the range of cost coefficients we also generated problems with $1 \leqslant a_{i j} \leqslant 999$ and $40 \leqslant a_{i j} \leqslant 50$.
The results gave about the same tendencies.
Finally the selection of column $j_{0}$ in step 1 of the algorithm was changed as follows:
Step 1: Select the first infeasible column $j_{0}$ and determine

$$
\bar{a}_{i_{0} j_{0}}=\operatorname{Min}_{i}\left\{\bar{a}_{i j_{0}} \mid \bar{a}_{i j_{0}}<0\right\}
$$

The results were slightly higher CPU-times, numbers of degenerate steps and iterations.

TABLE I
results on fixed (random) problems


Remarks: $1 \leqslant \mathrm{a}_{\mathbf{i j}} \leqslant 99$, CPU-times in 0,1 secs.

TABLE II
Average Results on random problems

| $n$ | $\mathrm{n}^{+}$ | deg | it | T | $\begin{gathered} \text { Tomizawa } \\ T \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | 8,0 | 0 | 2,0 | 2,0 | 1,5 |
| 20 | 17,2 | 0,4 | 4,0 | 8,4 | 6,3 |
| 30 | 24,0 | 1,0 | 5,8 | 25,2 | 20,3 |
| 50 | 38,8 | 1,2 | 10,0 | 103,0 | 69,9 |
| 80 | 64,6 | 1,4 | 13,8 | 336,6 | 300,6 |
| 100 | 79,8 | 1,0 | 18,4 | 704,0 | 536,0 |

Remarks:
5 problems in each problem size $1 \leqslant a_{i j} \leqslant 99$
CPU-times in 0,1 secs initialization $\mathrm{I}_{3}$
$\mathrm{n}^{+}=$number of nonnegative columns in the reduced-cost matrix after initialization
deg= number of degenerate steps
it $=$ total number of iterations
$T=$ CPU-time

Concluding remarks: In the average and using initialization method $\mathrm{I}_{3}$
it seems that: Total number of iterations $\cong 0,19 . n$

$$
\begin{aligned}
\text { CPU-time "primal" } & \cong 1,3 . \text { "Tomizawa" } \\
\mathrm{n}^{+} & \cong 0,8 \cdot \mathrm{n} \\
\mathrm{deg} & \cong(0-0,1) \cdot \mathrm{n}
\end{aligned}
$$

## References

[1] Balinski, M.L. and Gomory, R.E.: "A primal method for the assignment and transportation problems", Man. Sc.,Vol 10, No 3 (1964).
[2 ] Dorhout, B.: "Experiments with some algorithms for the linear assignment problem", Report BW 39/77, Mathematisch Centrum, Amsterdam (1977).
[3] Hung, M.S. and Rom, W.O.: "Solving the assignment problem by relaxation", Op. Res., Vol 28, No 4 (1980).

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